

LPMS-IG1

LPMS Low-Drift, Low-Noise Inertial Measurement Unit (IMU)

with CAN Bus / RS232 Connectivity

The LPMS-IG1 is a 9-axis inertial measurement unit (IMU) offering high precision orientation and linear acceleration measurements in an IP67-rated enclosure. It is equipped with a powerful central processing unit fusing raw data from gyroscope, accelerometer, magnetometer to calculate results on the fly with low drift and high accuracy. LPMS-IG1 perfectly fits application cases in an industrial environment where motion measurements with high precision and low latency are required.

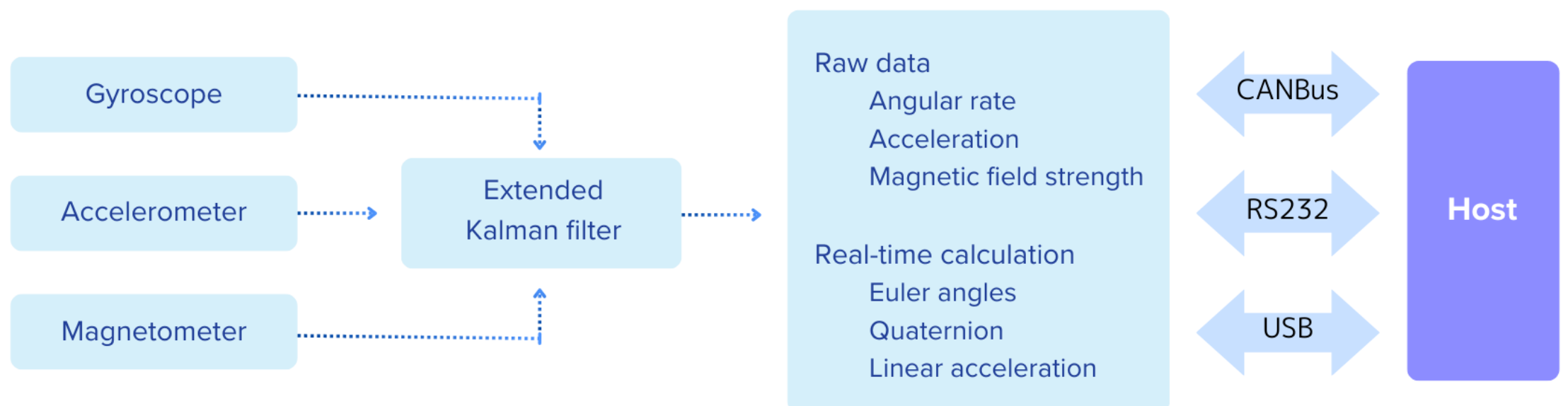


Key Features

- MEMS-based 9-axis inertial measurement unit (IMU) with on-board sensor fusion
- Very low-noise gyroscope for low-drift measurements with a bias stability of 4°/hour
- Dual gyroscope mode with additional high-range gyroscope for measurements above 400°/s up to 2000°/s
- Real-time, on-device calculation of sensor orientation and linear acceleration
- CAN bus (partial CANopen support) or RS232 communication interface options (all models include a USB connection)
- IP67 rated housing (dustproof and waterproof)
- Versatile software and library support for data acquisition and sensor configuration

Application

- Robot manipulator forward kinematics control
- Automotive dead reckoning
- Object orientation tracking for VR/AR
- Automatic guided vehicle (AGV) navigation

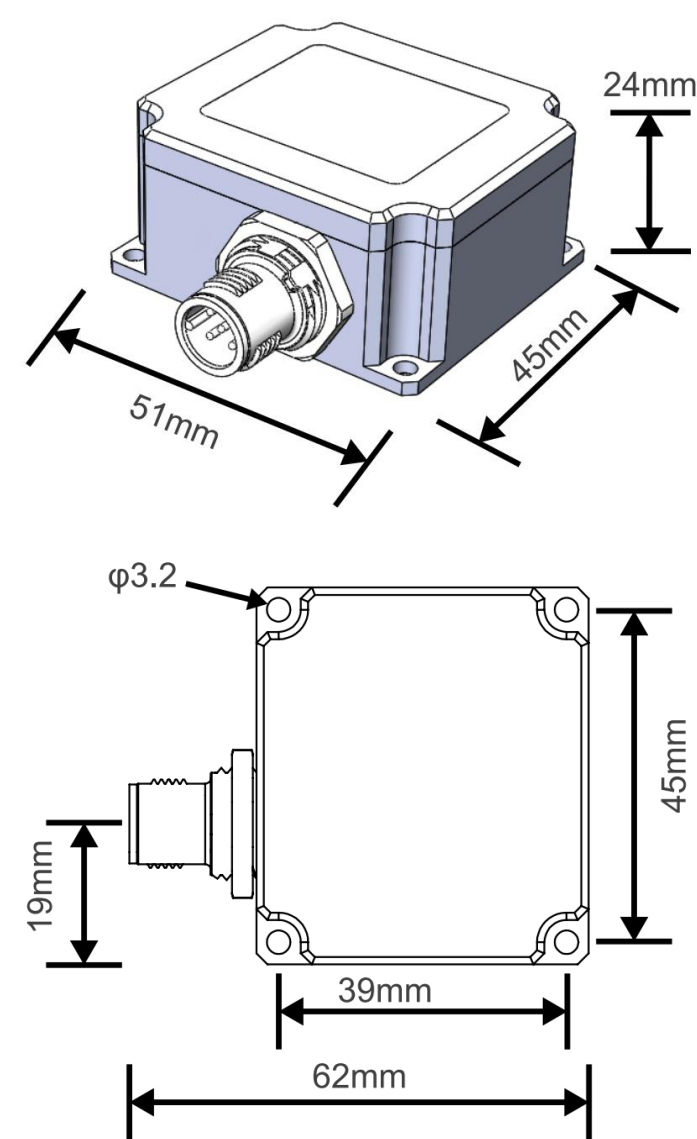


Sensor Specification

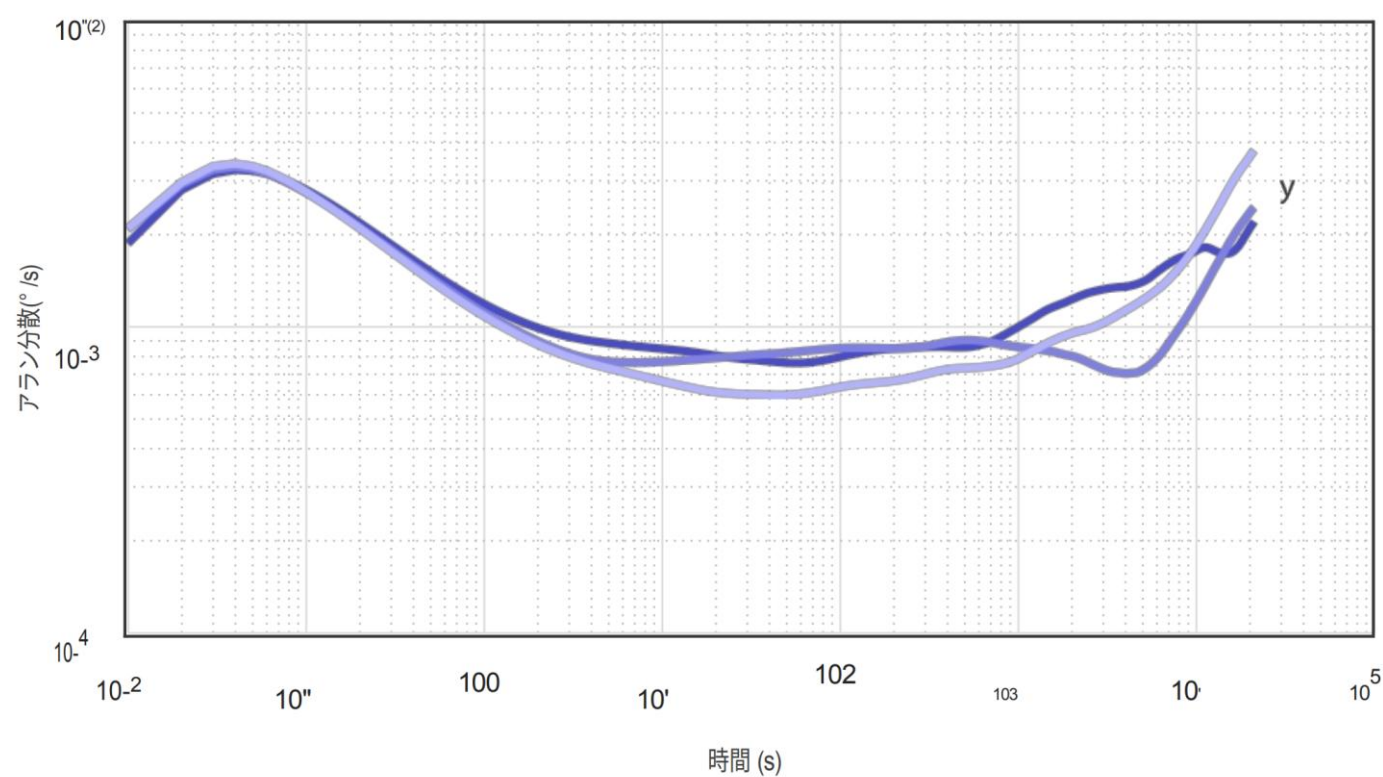
| Part Number | LPMS-IG1 CAN | LPMS-IG1 RS232 | LPMS-IG1 RS485 |
|------------------------------|---|-------------------------|-----------------------|
| Communication Interface | CAN BUS, USB | RS232, USB | RS485, USB |
| Max. Baudrate | 1M bit/s | 921600 bit/s | 256000 bit/s |
| Communication Protocol | LP-CAN / CANopen | LP-BUS/ ASCII | LP-BUS/ ASCII |
| Size | 51 x 45 x 24 mm | | |
| Weight | 74 g | | |
| Orientation Range | Roll: ±180°; Pitch: ±90°; Yaw: ±180° | | |
| Resolution | 0.01° | | |
| Accelerometer | 3-axis, ±2 / ±4 / ±8 / ±16 g, 16 bits | | |
| Gyroscope | Dual gyroscope design: #1: 3-axis, ± 400 dps, 24 bit, #2: 3-axis, ± 1000 / ± 2000 dps, 16 bit | | |
| Static Orientation Stability | #1:4°/hour, #2: 6°/hour | | |
| Gyroscope Noise Density | #1: 0.002 dps/√Hz, #2: 0.004 dps/√Hz | | |
| Magnetometer | 3-axis, ±2 / ±8 gauss, 16 bits | | |
| Data Output Format | Raw data / Euler angle / Quaternion | | |
| Data Transmission Rate | 5 ~ 500 Hz | | |
| Power Consumption | 0.252 (0.021A@ 12 V) | 0.216 (0.018A@ 12 V) | 0.24 (0.02A@ 12 V) |
| Power Supply | 5 V ~ 36 V DC | | |
| Connector | M12 8 Pin (SACC-DSI-MS-8CON-PG 9/0,5 SCO equivalent) | | |
| Case Material | Aluminum ally, IP67 Waterproof | | |
| Temperature Range | -20 to +80 °C (upon request -40 to +80 °C) | | |

• Performance parameters are measured at +25°C. Other temperatures may result in varying reference values.
※Please refer to the product manual for more detailed specifications.

External Dimensions



LPMS-IG1 High Precision Gyroscope (#1) Allan Variance Plot



Package

- LPMS-IG1 Sensor x 1
- User Guide Card x 1
- Cable x 1
- Box x 1
- Warranty (1 Year)