

LPMS-IG1

LPMS Low-Drift, Low-Noise Inertial Measurement Unit (IMU) with CAN Bus / RS232 Connectivity

The LPMS-IG1 is a 9-axis inertial measurement unit (IMU) offering high precision orientation and linear acceleration measurements in an IP67-rated enclosure. It is equipped with a powerful central processing unit fusing raw data from gyroscope, accelerometer, magnetometer to calculate results on the fly with low drift and high accuracy. LPMS-IG1 perfectly fits application cases in an industrial environment where motion measurements with high precision and low latency are required.

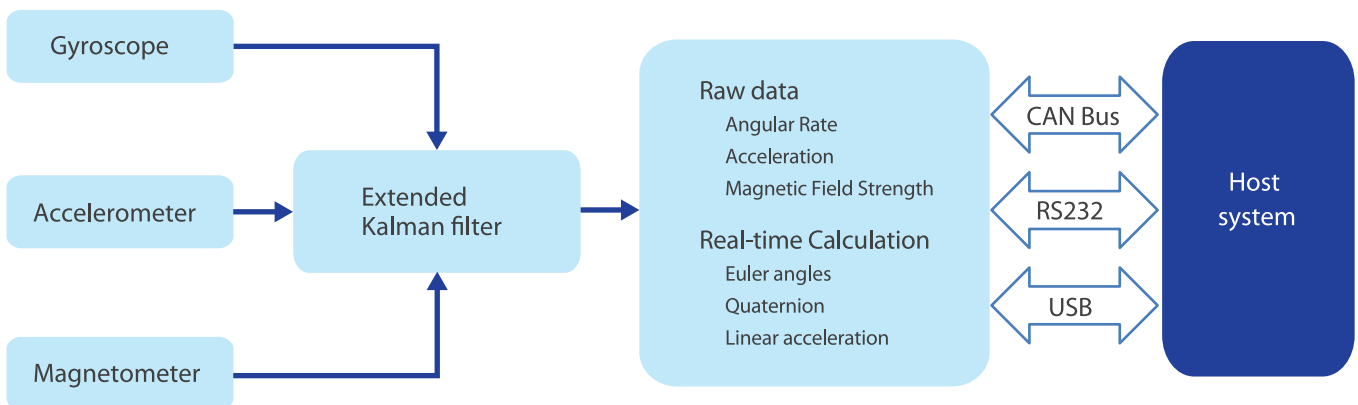


Key Features

- MEMS-based 9-axis inertial measurement unit (IMU) with on-board sensor fusion
- Very low-noise gyroscope for low-drift measurements with a bias stability of 4°/hour
- Dual gyroscope mode with additional high-range gyroscope for measurements above 400°/s up to 2000°/s
- Real-time, on-device calculation of sensor orientation and linear acceleration
- CAN bus (partial CANopen support) or RS232 communication interface options. All models include a USB connection.
- IP67 rated housing (dustproof and waterproof)
- Versatile software and library support for data acquisition and sensor configuration

Potential Applications

- Robotic manipulator forward kinematics control
- Automotive dead reckoning
- Object orientation tracking for VR/AR
- Automatic guided vehicle (AGV) navigation



For pricing or any further information, please contact Omni Instruments Ltd.

Contact Details:

Tel: +44 1382 443000
Fax: +44 1382 453197
Email: info@omni.uk.com

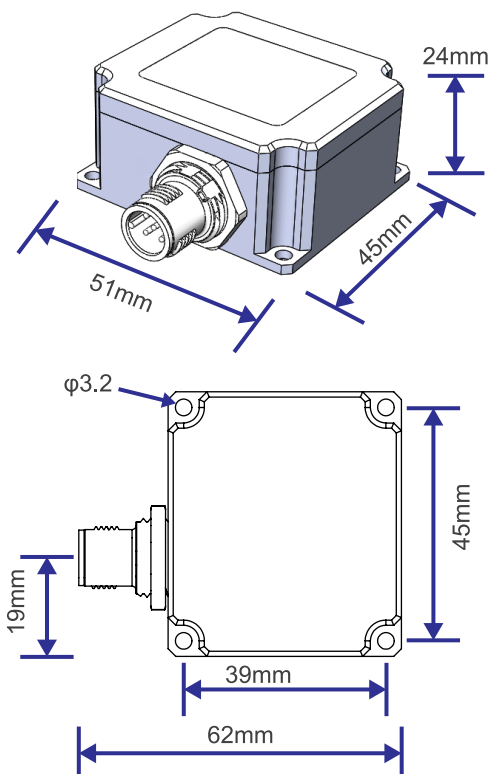
Mailing Address: Unit 1, 14 Nobel Road,
Wester Gourdie Industrial Estate,
Dundee, DD2 4UH.

Website: www.omniinstruments.co.uk

Sensor Specifications

Product name	LPMS-IG1 CAN	LPMS-IG1 RS232
Wired interface	CAN Bus, USB	RS232, USB
Baudrate	1M bit/s	921600 bit/s
Communication protocol	LP-CAN / CANopen	LP-BUS
Size	51 x 45 x 24 mm	
Weight	74 g	
Orientation range	Roll: $\pm 180^\circ$; Pitch: $\pm 90^\circ$; Yaw: $\pm 180^\circ$	
Orientation resolution	0.01°	
Accelerometer	3-axis, $\pm 2 / \pm 4 / \pm 8 / \pm 16$ g, 16 bits	
Gyroscope	Dual gyroscope design: #1: 3-axis, ± 400 , 24 bits #2: 3-axis, $\pm 1000 / \pm 2000$ dps, 16 bits	
Static orientation stability	#1: 4°/hour, #2: 6°/hour	
Gyroscope noise density	#1: 0.002 dps/ $\sqrt{\text{Hz}}$, #2: 0.004 dps/ $\sqrt{\text{Hz}}$	
Magnetometer	3-axis, $\pm 2 / \pm 8$ gauss, 16 bits	
Data output format	Raw data / Euler angle / Quaternion	
Data output rate	5 ~ 500 Hz	
Power consumption	≤ 400 mW @12 V	
Power supply	5 V ~ 24 V DC	
Connector	Signal connector: M12	
Housing	Aluminum, IP67 rated	
Temperature range	-20 ~ +80°C	

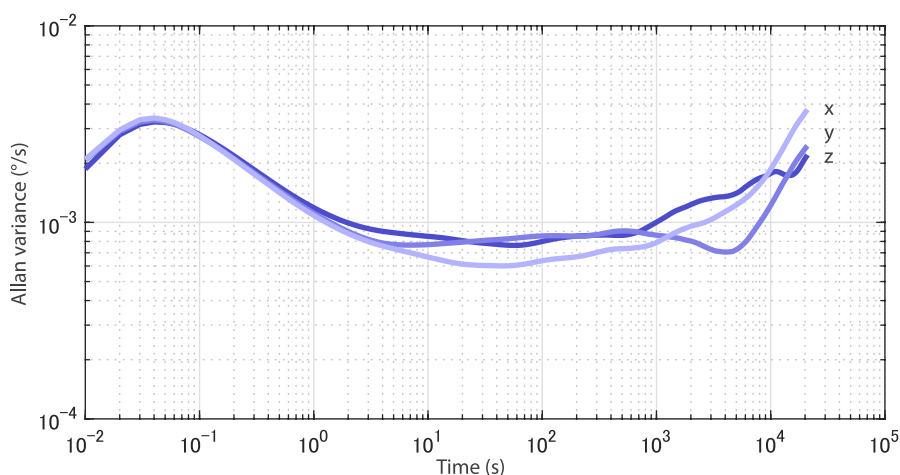
Mechanical Drawing



Package Contents

- LPMS-IG1 sensor x 1
- User guide card x 1
- Cable x 1
- Box x 1
- Warranty (1 year)

LPMS-IG1 High Precision Gyroscope (#1) Allan Variance Plot



Whilst every effort has been made to ensure the accuracy of this specification, we cannot accept responsibility for damage, injury, loss or expense from errors or omissions. In the interest of technical improvement, this specification may be altered without notice.

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